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Eidgenössisches Departement des Innern EDI **Bundesamt für Meteorologie und Klimatologie MeteoSchweiz**

Numerical Weather Prediction

on GPUs at MeteoSwiss

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Why using Domain Specific Language (DSL) in weather and climate ?

- DSL : computer language restricted to a particular domain
- We need performance to reach time to solution

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- Separation of concern between domain and computer scientist
- Single source code for multiple target architectures
- Possible to write a new backend when a new technology emerged
- Allow aggressive optimization without degrading readability of user code
- Allow optimization across components data centric optimization

time-to-solution for weather forecasting - MeteoSwiss, the Federal Office of Meteorology and Climatology, today reported its next generation COSMO-1 forecasting system is now operational. COSMO-1 requires 20 times the computing power of COSMO-2 and runs on the hybrid CPU-GPU supercomputer, Piz Kesch, operated by the Swiss National Supercomputing Centre (CSCS) and custom built in collaboration with Cray and NVIDIA.

COSMO-1 was put into service last September (see, Today's

- Solution to Build Mas:
- ASRock Rack to Exhib

COSMO model on GPU w

 $\mathbf{r} = \mathbf{r} \cdot \mathbf{r} + \mathbf{r} \cdot \mathbf{r} + \mathbf{r} \cdot \mathbf{r} + \mathbf{r} \cdot \mathbf{r} + \mathbf{r} \cdot \mathbf{r}$

- Local area numerical weather prediction and climate model (cosmo-model.org), 350 KLOC F90 + MPI
- Full GPU port strategy : avoid GPU-CPU data transfer
- Approach: OpenACC compiler directives + Domain Specific Language (DSL) re-write
- 4-5x faster on GPU (socket to socket comparison)

IJ STELLA DSL for COSMO

```
First generation of DSL for weather
models (C++, template metaprogramming)
```
};

template<tvpename TEnv> struct Divergence { STENCIL STAGE(TEnv)

```
STAGE PARAMETER(FullDomain, phi)
STAGE<sup>-</sup>PARAMETER(FullDomain, lap)
STAGE PARAMETER(FullDomain, flx)
static void Do(Context ctx, FullDomain) {
  ctx[div::Center()]=ctx[phi::Center()]-ctx[alpha::Center()] * (ctx[fix::Center() -\textsf{ctx}[flx::At(iminus1)] + \textsf{ctx}[fly::Center() -ctx[fly::At(jminus1)])
}
```

```
IJKRealField dataIn, dataOut;
```

```
Stencil stencil:
StencilCompiler::Build(
  stencil.
  pack parameters(
    Param<res, clnOut>(dataOut),
    Param<phi, cln)(dataIn)
    Param<alpha, cln)(dataAlpha)
  define temporaries(
    StencilBuffer<lap, double, KRange<FullDomain,0,0> >(),
    StencilBuffer<flx, double, KRange<FullDomain,0,0> >(),
    StencilBuffer<fly, double, KRange<FullDomain, 0.0> >()
  ,
 define loops(
    define sweep<cKIncrement>(
      define stages(
        StencilStage<Lap, IJRange<cIndented, -1,1,-1,1> >()
        StencilStage\ltFlx, IJRange\ltcIndented, -1,0,0,0> > (),
        StencilStage\ltFly, IJRange\ltcIndented, 0, 0, -1, 0 > \gt (),
        StencilStage<Divergence, IJRange<cComplete,0,0,0,0>
```
U Lessons learned from COSMO port to GPU

• Stable operation at MeteoSwiss since 2016, 2 generations Cray Hybrid GPU systems

OpenACC:

- + Incremental insertion in existing code, good acceptance by domain scientist
- Some compiler bugs/issues, legacy code: no unittest, not always performance portable, only nvidia GPU (at this point), !\$acc/omp conquer your code, !\$acc is not comments but code. Costly maintenance

DSL dycore:

+ Separation of concerns, performance portable : tested on CPU, supports various hardware architecture (Nvidia, AMD GPU, Intel MIC, easier to test and maintain (unittest)

DSL supported features, hard to debug (C++ Meta Programming) - Low acceptance, new syntax and black box, requires new know how, limited to

IJ ICON port to GPU

- ICON: Non-hydrostatic global and regional unified climate and numerical weather prediction model.
- ICON partners: DWD, MPI-M, DKRZ, KIT ICON dev. Partners: COSMO, C2SM ...
- Initial GPU port: OpenACC only, accepted by all partners, step by step integration in official version (MeteoSwiss, C2SM, CSCS, DWD, DKRZ, MPI-M)
- DSL implementation of components research projects : ESCAPE, ESiWACE, EXCLAIM, WarmWorld

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IJ Porting strategy ICON: OpenACC

- Avoid GPU-CPU transfer: all components of the time loop need to be ported to GPU
	- Exception: Data assimilation runs on CPU
- Design : Main parallelization along horizontal blocking (nproma not at the block level like OpenMP for CPU)
	- Use large nproma when running on GPU (ideally 1 single block per GPU)
	- Compatible with COSMO parameterizations already ported to GPU
- Testing:
	- Individual components with Serialbox and PCAST (Nvidia compiler tool) during development
	- Comparing model output with tolerance (CPU/GPU not bit-identical)
- All components for NWP Regional application ported, optimization work ongoing.
- Port of components for the global setup ongoing

CPU – GPU comparison (socket to socket)

Operational ICON-2 (2 km. Alps) 8 Nodes, 1h, P100 GPU vs Intel Xeon E5 12 cores (Piz Daint, CSCS, GPU node)

Overall improvement ca 4.2x, optimization ongoing.

Note : this is not enough for operational requirement at MeteoSwiss, slower compare to COSMO

Porting and optimization challenges

OpenACC optimizations Conceptual challenges

- GPU and CPU working asynchronously
	- Reduces launch overhead
- Bundling similar loop constructs into single GPU kernels
	- Improves cache reuse
	- Reduces launch overhead
- Compiler assisted / manual inlining of function calls
	- Required for complex (deep call-trees) GPU kernels
	- Enables optimizations above

- Tiling for surface and turbulence
	- Implicitly introduces sub-blocking which leads to underutilized GPUs
- Physics initialization on CPU
	- Prohibitively slow because of unsuitable nproma and MPI settings for CPU
- **Radiation sub-blocking**
	- Radiation (ec-rad) has an additional dimension which can be parallelized Subblocking as a memory optimization
- Code management
	- Disruptive code changes are challenging
	- ecrad: juggling diverse interests

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    GPU Port Technologies (OpenACC)
```
OpenACC+Fortran :

- Many ifdef
- Limited optimization margin
- Currently only works on Nvidia GPUs

```
#ifdef OPENACC
!SACC PARALLEL &
!$ACC PRESENT( p patch, p prog, p diag, z vt ie ), IF( i am accel node .AND. acc on )
! SACC LOOP GANG
#else
!SOMP DO PRIVATE(jb, jk, je, i startidx, i endidx) ICON OMP DEFAULT SCHEDULE
#endif
     DO ib = i startblk, i endblk
        CALL get indices e(p patch, jb, i startblk, i endblk, &
                           i startidx, i endidx, rl start, rl end)
        ! Compute v*grad w on edges (level nlevp1 is not needed because w(nlevp1) is diagnostic)
       ! Note: this implicitly includes a minus sign for the gradients, which is needed later on
!SACC LOOP VECTOR COLLAPSE(2)
#ifdef LOOP EXCHANGE
       DO je = i startidx, i endidx
!DIRS IVDEP
          DO jk = 1, nlev
            z v grad w(jk,je,jb) = p diag%vn ie(je,jk,jb) * p patch%edges%inv dual edge length(je,jb)* &
             (p \text{ proq%}w(\text{icidx}(ie, ib, 1), ik, \text{icblk}(ie, ib, 1)) - p \text{ proq%}w(\text{icidx}(ie, ib, 2), ik, \text{icblk}(ie, ib, 2))) &
             + z vt ie(je,jk,jb) * p patch%edges%inv primal_edge_length(je,jb) *
                                                                                                           \mathcal{R}_{\mathbf{f}}p patch%edges%tangent orientation(je.jb) *
                                                                                                            \mathbf{g}(z \le y \le (ik, ividx(je,jb,1),ivblk(je,jb,1)) - z \le (ik, ividx(je,jb,2),ivblk(je,jb,2)))#else
       DO ik = 1. nlev
          DO je = i startidx, i endidx
            z v grad w(je,jk,jb) = p diag%vn ie(je,jk,jb) * p patch%edges%inv dual edge length(je,jb)* &
             (p \text{ prog)} (icidx(je,jb,1),jk,icblk(je,jb,1)) - p prog%w(icidx(je,jb,2),jk,icblk(je,jb,2))) &
             + z vt ie(je,jk,jb) * p patch%edges%inv primal edge length(je,jb) *
                                                                                                            &
             p patch%edges%tangent orientation(je,jb) *
                                                                                                             \mathbf{R}(z_w(vividx(je,jb,1),jk,ivblk(je,jb,1)) - z_w(vividx(je,jb,2),jk,ivblk(je,jb,2)))#endif
          ENDDO
        ENDDO
     ENDDO
#ifdef OPENACC
!$ACC END PARALLEL
#else
!SOMP END DO
                                                                \sim 12
#endif
    ENDIF
```
ICON with Data Assimilation on GPU

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- Kilometer-Scale Ensemble Data Assimilation (KENDA). Calculations in ensemble space spanned by the ensemble members, using observations to compute analysis
- Assimilation component takes the model and compares them with observations (DACE) – wirte feedback files (fof)

Data Flow, and GPU strategy

• DACE code is not ported to GPU. The DACE code is kept on the CPU. Data is copied from GPU to CPU when needed.

High level DSL for ICON

- Need to support unstructured grid, such as ICON grid
- New abstraction (e.g. neighbors operations)
- Focus on usability, productivity. Should be usable for domain scientist
- High level python dsl (gt4py)
- Development work in several projects, ESCAPE, EXCLAIM(ETHZ)

• Performance :

…

- CUDA code generation for GPU : allow more optimization than OpenACC
- long term perspective data centric optimization across components, e.g. fusion

EXCLAIM Goals and Use Cases

Aims at developing an ICON- model based infrastructure, in particular using DSL, that is capable of running kilometer- scale climate simulations at both regional and global scales – C2SM, ETHZ, MeteoSwiss, CSCS

Motivation IJ

$$
\underline{\nabla}_{\underline{n}}\psi(e) = \frac{\psi(c_1(e)) - \psi(c_0(e))}{\hat{l}}
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#ifdef OMP !\$OMP #else !\$ACC #endif DO jb = i startblk, i endblk CALL get_indices_e(ptr_patch, ...) #ifdef __LOOP_EXCHANGE DO je = i startidx, i endidx DO $jk = slev$, elev #else DO $jk = slev$, elev DO je = i startidx, i endidx #endif **grad_norm_psi_e**(je,jk,jb) = & (**psi_c**(iidx(je,jb,**2**),jk,iblk(je,jb,2)) **psi_c**(iidx(je,jb,**1**),jk,iblk(je,jb,1))) / ptr_patch%edges%**lhat**(je,jb) ENDDO END DO END DO #ifdef OMP 0 !\$OMP ... 유 4 #else сÞ ф 45 83 $!$ \$ACC $...$ 43 상
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Motivation IJ

grad_norm_psi_e = sum_over(psi_c, Edge > Cell, [1/lhat, -1/lhat])

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#ifdef OMP !\$OMP #else !\$ACC #endif DO jb = i startblk, i endblk CALL get_indices_e(ptr_patch, ...) #ifdef LOOP EXCHANGE DO je = i startidx, i endidx DO $jk = slev$, elev #else DO $jk = slev$, elev DO je = i startidx, i endidx #endif **grad_norm_psi_e**(je,jk,jb) = & (**psi_c**(iidx(je,jb,**2**),jk,iblk(je,jb,2)) **psi_c**(iidx(je,jb,**1**),jk,iblk(je,jb,1))) / ptr_patch%edges%**lhat**(je,jb) ENDDO END DO END DO #ifdef OMP 0 !\$OMP ... 유 4 #else -c'h ф 45 83 $!$ \$ACC $...$ 43 람
답 #endif xavier.lapillonne@meteoswiss.ch 18 īg, 4 ďЪ еЪ

Python DSL notation example 0 (Dusk/Dawn) : Neighbor Chains

@stencil def intp(fc: Field[Cell], fe: Field[Edge], w: Field[Cell > Edge > Cell > Edge]): with levels downward: fc = **sum_over**(Cell **> Edge >** Cell **> Edge**, $w*fe$

O Performance of ICON dycore (DSL) prototype

Open ACC vs DSL

• $\;$ DSL dycore about 40% faster then OpenACC - not fully optimized. Dry dycore only.

Conclusions

- COSMO model has been ported to GPU using DSL and OpenACC compiler directives, and is running in operation since 2016.
- Similar approach is considered for the ICON model, with a first version only based on compiler directives
- New High level DSL are being developed in particular in the EXCLAIM project
	- Separation of concern between scientist and computer engineer
	- More aggressive optimization and data centric optimization across components
	- Target more architectures
	- Improve usability and maintenance

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Challenges using DSL in weather and climate

- How to bring along the scientific community: why changing ? Training, new learnings, keep productivity
- The quality level need to be high to keep user in the loop, need to be user friendly
- Need to achieve significant performance improvement to convince developers that this is the way forward
- Ensure and guarantee long term maintenance of the DSL infrastructure at a community level.
- DSL only work within the implemented pattern, how to let scientist have freedom to explore idea outside of this domain

Additional slides

Status of OpenACC performance

Parametrization

C2SM / EXCLAIM project

EXascale Computing platform for cLoud-resolving weAther and clImate Models

Goals:

MeteoSchweiz

- develop an extreme scale computing and data platform for cloud resolving weather and climate modeling – prepare for exascale system
- redesign the codes in the framework of python base domain-specific languages
- exploit efficiency gains at both the computational and algorithmic levels
- develop an analysis and storage framework to deal with the exabytes of data generated
- design concrete applications addressing scale-interactions in the ocean and atmosphere
- Performance target : 1 simulated year / day ω 1 km global

Large project : 1. Senior scientist, 2 post-docs, 6 Software eng. + in in kind contributions from ETHZ, CSCS, EMPA, SDSC and MeteoSwiss

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Multi-core vs. GPU-accelerated hybrid

Performance Results

MeteoSchweiz

- Test Setup as close as we can get right now to the operational setup:
	- − Ca. 1.2M Grid columns (Area over Switzerland & Germany)
	- − Simulation time of one hour
	- − Run on Piz Daint 32 GPU nodes

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U Performance : strong scaling (QUBICC conf.)

Strong scaling , 160/20/2.8 km, 191 levels, 180 steps

CPU: 1xHaswell, 12 ranks/node, OMP=2 (CCE) GPU: 1xP100 (daint-gpu), 2 ranks/node (PGI)