

Ensemble copula coupling (ECC): Application to the ECMWF ensemble

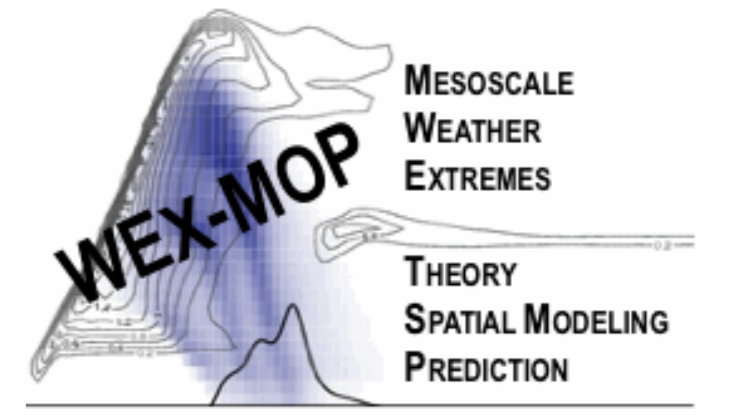


Roman Schefzik^{1,*}, Thordis Thorarinsdottir² and Tilmann Gneiting¹

¹Institute for Applied Mathematics, Heidelberg University, Germany

²Norwegian Computing Center, Oslo, Norway

*r.schefzik@uni-heidelberg.de



Introduction

- Forecast ensembles typically require statistical postprocessing to address biases and dispersion errors.
- Widespread state-of-the-art univariate ensemble postprocessing methods are
 - Bayesian model averaging (BMA) [6] and
 - Ensemble model output statistics (EMOS) [2].
- These methods only apply to a *single* weather quantity at a *single* location for a *single* look-ahead time.
- However, physical consistency of multivariate dependencies across space, time and variables is required in numerous applications, such as air traffic management.
- Recent multivariate ensemble postprocessing methods include among others
 - Bivariate postprocessing of (u, v) -wind vectors [5] [7] and a
 - Gaussian copula approach [4].

Our proposal: **ensemble copula coupling (ECC)**

discrete copula-based and non-parametric approach, which retains the spatial, temporal and inter-variable rank dependence patterns of the raw ensemble

The ECC approach

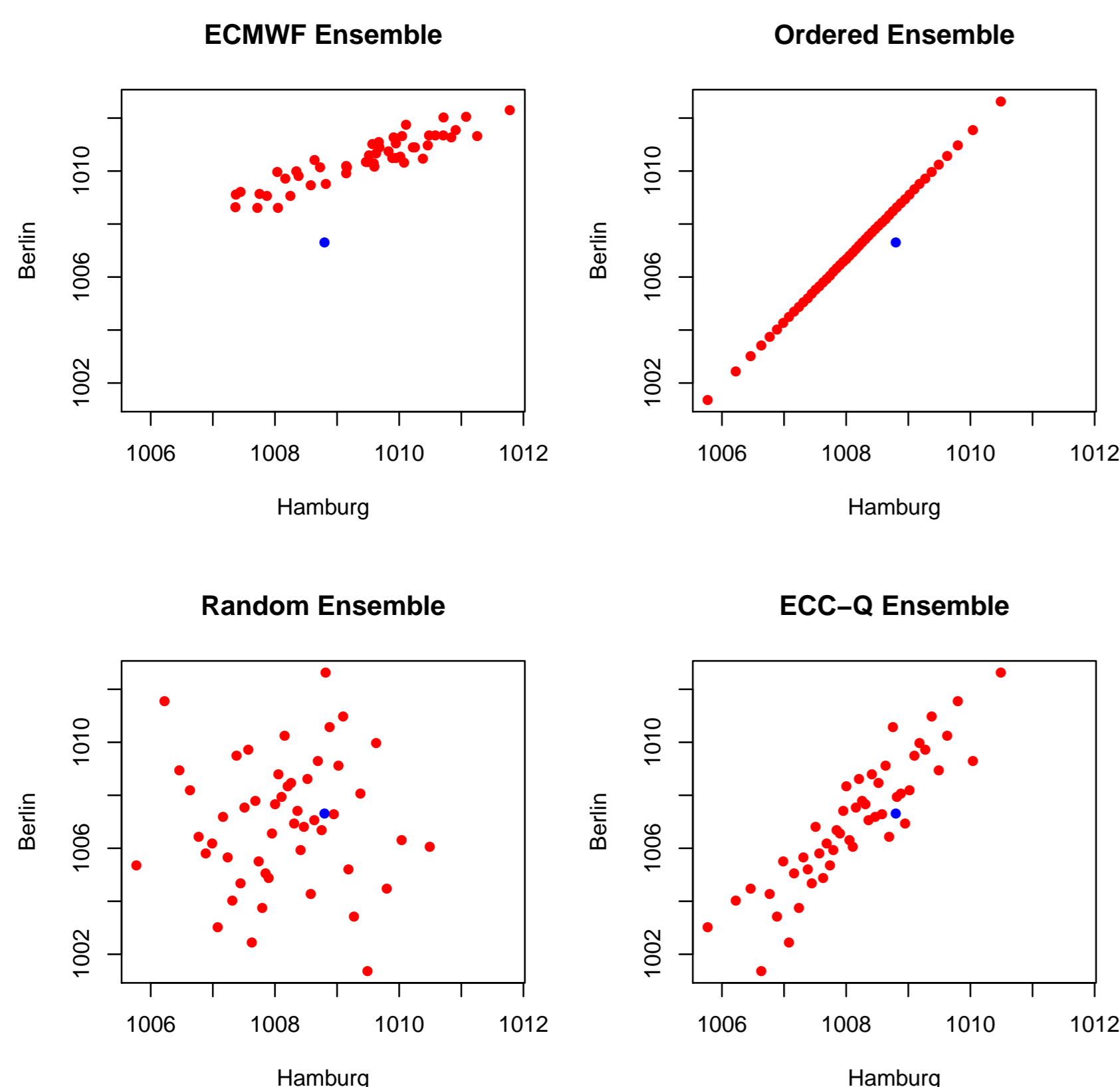


Figure 1: 48 hour pressure forecasts (in hPa) at Berlin and Hamburg valid 0000 UTC on 18 September 2010. The verifying observation is indicated by the blue dot.

1. Raw ensemble: For each variable $i \in \{1, \dots, I\}$, location $j \in \{1, \dots, J\}$ and prediction horizon $k \in \{1, \dots, K\}$, find the raw ensemble forecast $x_{1, \dots, M}^{\ell}$, where $\ell := (i, j, k) \in \{1, \dots, L\}$, and L is the number of possible combinations of i, j and k .

For each fixed ℓ , determine the corresponding order statistics $x_{(1)}^{\ell} \leq \dots \leq x_{(M)}^{\ell}$, with ties resolved at random, by computing the permutation σ_{ℓ} of $1, \dots, M$ given by

$$\sigma_{\ell}(m) := \text{rank}(x_m^{\ell}) \text{ for all } m \in \{1, \dots, M\}.$$

2. Univariate postprocessing: Use univariate postprocessing methods to obtain calibrated and sharp predictive distributions $F_{X^{\ell}}$ for each variable, location and look-ahead time individually.

3. Quantization: For each ℓ , generate M samples $\tilde{x}_1^{\ell}, \dots, \tilde{x}_M^{\ell}$ from $F_{X^{\ell}}$, which can be done in various ways:

- **ECC-R:** Take simple random samples.
- **ECC-P:** Take the quantiles of $F_{X^{\ell}}$ that correspond to the Pearson residuals of the ensemble values [5].
- **ECC-Q:** Take the equidistant $\left(\frac{m-0.5}{M}\right)_{m=1, \dots, M}$ -quantiles of $F_{X^{\ell}}$ (idea from e.g. [1]) \rightarrow our preferred variant.

4. Reordering/ECC: For each ℓ , the ECC ensemble is given by $\hat{x}_1 := \tilde{x}_{(\sigma_{\ell}(1))}^{\ell}, \dots, \hat{x}_M := \tilde{x}_{(\sigma_{\ell}(M))}^{\ell}$.

By applying the empirical raw ensemble copula to the samples from step 3, it inherits the multivariate rank dependence structure from the raw ensemble.

Multivariate verification methods

Goal of probabilistic forecasting: maximize sharpness subject to calibration.

- Multivariate rank histogram (MRH) [3] to check calibration:
 - flat MRH indicates calibrated ensemble,
 - (inverse) U-shaped MRH indicates underdispersive (overdispersive) ensemble,
 - skewed MRH indicates biased ensemble.
- Energy score (ES) [3] for discrete distributions as an overall performance measure (the lower the better):

$$ES(P_{\text{ens}}, \mathbf{x}) = \frac{1}{M} \sum_{m=1}^M \|\mathbf{x}_m - \mathbf{x}\| - \frac{1}{2M^2} \sum_{n=1}^M \sum_{m=1}^M \|\mathbf{x}_n - \mathbf{x}_m\|,$$

where P_{ens} is the predictive distribution, M the ensemble size, $\mathbf{x}_1, \dots, \mathbf{x}_M \in \mathbb{R}^L$ the ensemble forecasts, $\mathbf{x} \in \mathbb{R}^L$ the observation vector and $\|\cdot\|$ the Euclidean norm.

Case study: The ECMWF ensemble over Germany

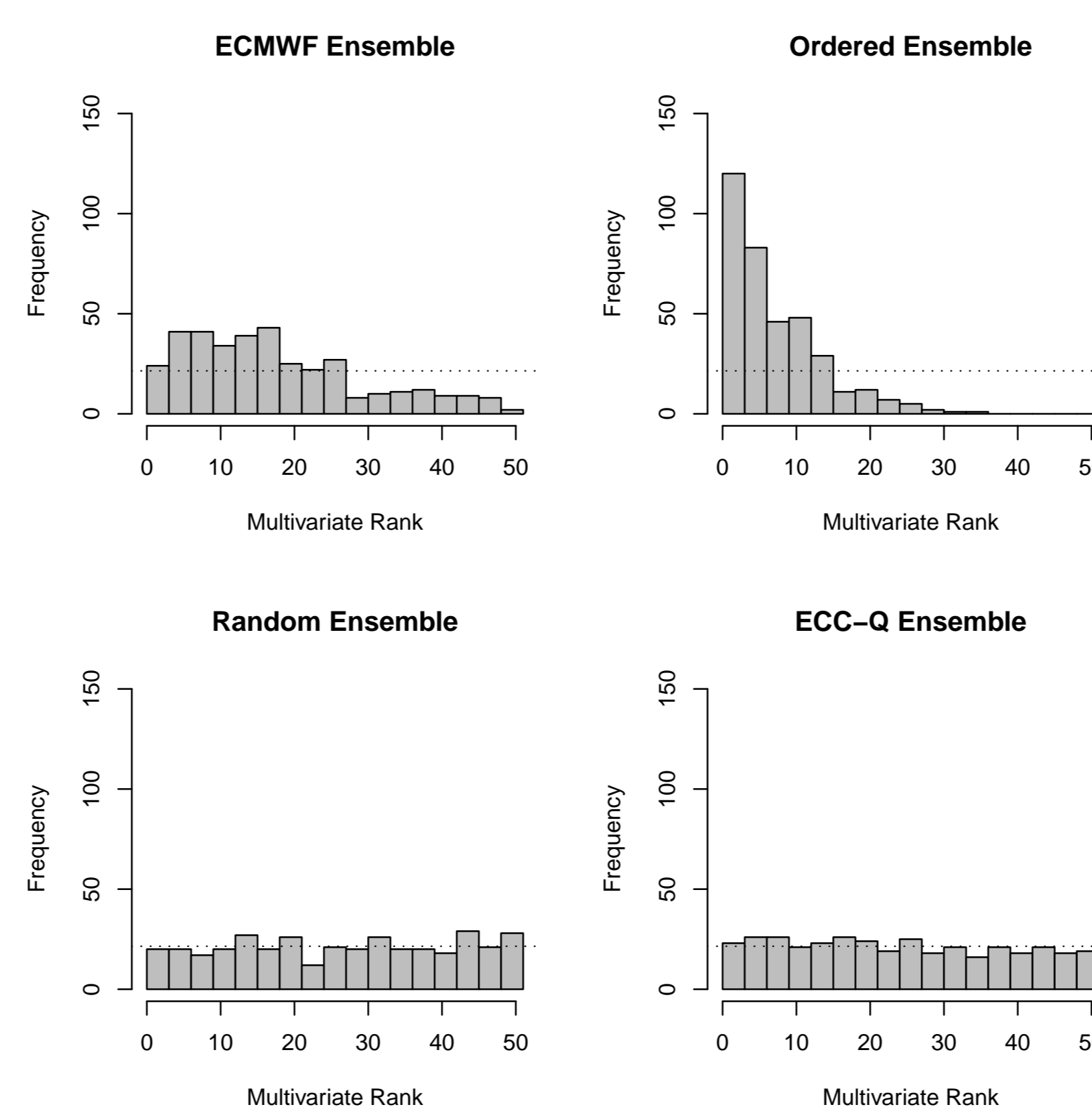


Figure 2: MRHs for 24 hour u -wind vector forecasts over an area in Upper Bavaria for 1 May 2010 to 30 April 2011

Table 1: Different quantization approaches and ECC: Average ES (in m/s) for 48 hour (u, v) -wind vector forecasts for 1 May 2010 to 30 April 2011.

Ensemble	Berlin	Frankfurt	Hamburg
ECMWF	1.21	1.66	1.30
ECC-R	1.10	1.44	1.18
ECC-P	1.10	1.43	1.17
ECC-Q	1.09	1.42	1.17

- European Centre for Medium-Range Weather Forecasts (ECMWF) ensemble with 50 exchangeable members
- Forecasts are available on a grid consisting of 1221 points over Germany and surrounding areas. Use the mean of the next day's 0 h ECMWF model nowcasts as the ground truth.
- Employ bilinearly interpolated forecasts and real observations for the locations Berlin, Hamburg and Frankfurt.
- Univariate postprocessing for each weather variable, location and prediction horizon is done either by BMA or EMOS, using a training period of 30 days.
- Use ECC-Q and sample the equidistant $\left(\frac{m-0.5}{50}\right)_{m=1, \dots, 50}$ -quantiles from each univariate predictive distribution.
- Create and compare different postprocessed ensembles:
 - Ordered quantiles (OQ) ensemble: $\left(\frac{m-0.5}{50}\right)_{m=1, \dots, 50}$ -quantiles in **increasing** order,
 - Random quantiles (RQ) ensemble: $\left(\frac{m-0.5}{50}\right)_{m=1, \dots, 50}$ -quantiles **randomly** ordered,
 - **ECC-Q** ensemble: $\left(\frac{m-0.5}{50}\right)_{m=1, \dots, 50}$ -quantiles ordered **with respect to the ECMWF raw ensemble ranks**.

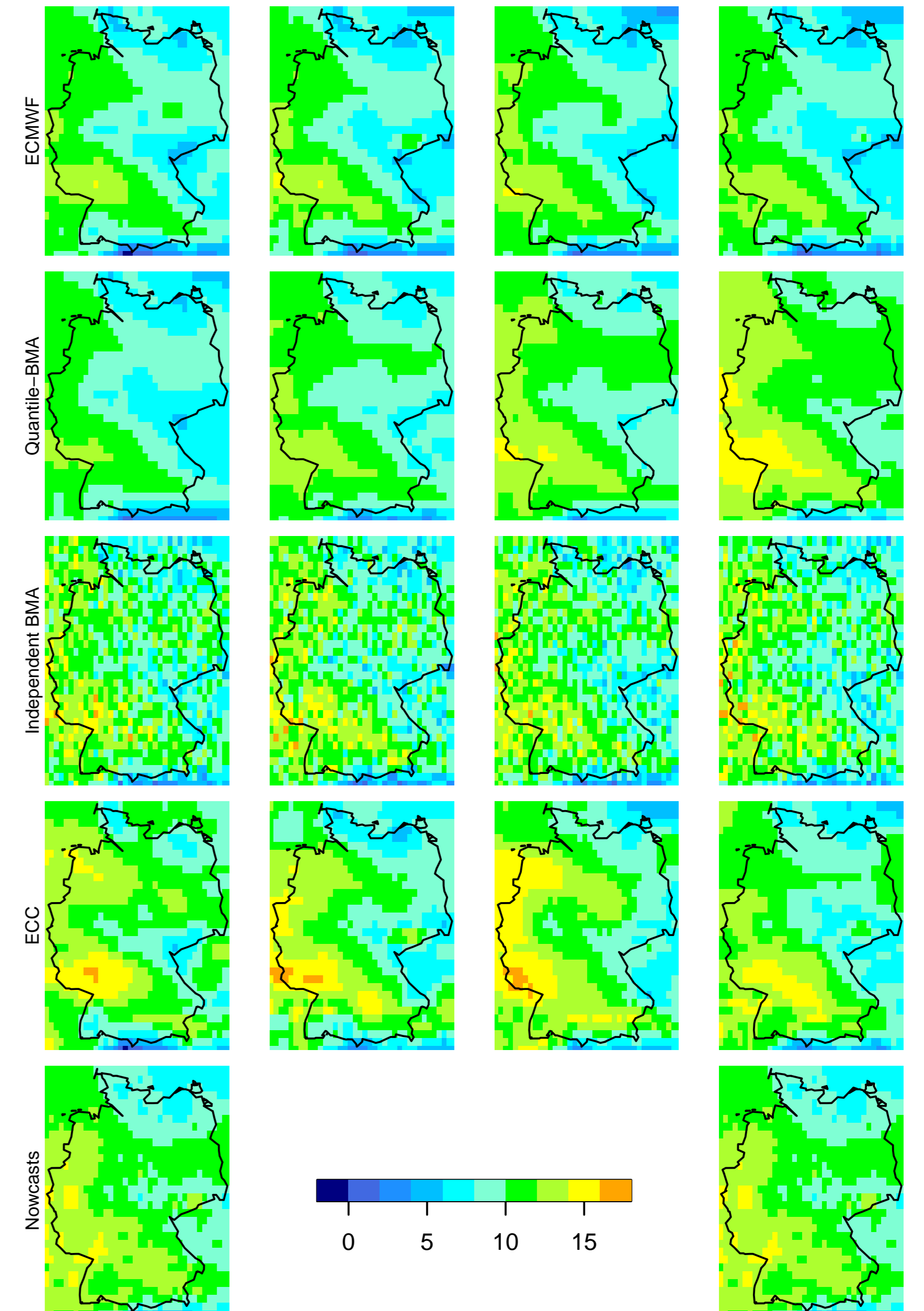


Figure 3: 24 hour temperature forecasts (in °C) over Germany valid 0000 UTC on 25 April 2011. First row: selected ECMWF ensemble members; second row: the 20th, 40th, 60th, and 80th quantiles from the BMA forecasts; third row: random independent realizations from the BMA forecasts; fourth row: ECC forecasts corresponding to the members in the first row; fifth row: the ensemble mean nowcasts.

Table 2: Average ES for 24 hour forecasts over contiguous test areas for 1 May 2010 to 30 April 2011.

		Area I: Baltic Sea	Area II: North Rh.- Westph.	Area III: Upper Bavaria	Area IV: Rhine- Neckar
Temp. (°C)	ECMWF	5.01	5.79	14.22	5.19
	OQ	4.48	5.08	10.63	4.30
	RQ	4.50	5.14	10.94	4.47
	ECC-Q	4.39	5.00	10.56	4.30
Pressure (hPa)	ECMWF	3.44	3.38	4.66	2.39
	OQ	2.84	3.09	3.98	2.07
	RQ	3.17	3.46	4.22	2.30
	ECC-Q	2.88	3.13	3.96	2.13
u -wind (m/s)	ECMWF	4.36	3.75	4.53	2.43
	OQ	4.36	3.78	4.51	2.45
	RQ	4.36	3.72	4.40	2.44
	ECC-Q	4.25	3.66	4.33	2.40

Summary of ECC

- Postprocessing tool retaining the spatial, temporal and inter-variable rank dependencies of the raw ensemble
- Connected to discrete/empirical copulas
- Simple and clear, yet powerful and well performing
- Easy to implement given R packages for univariate postprocessing, such as `ensembleBMA` or `ensembleMOS`

References

- [1] Bremnes, J. B. (2007). Improved calibration of precipitation forecasts using ensemble techniques. Part 2: Statistical calibration methods. Norwegian Meteorological Institute, Technical Report no. 04/2007, available online.
- [2] Gneiting, T., Raftery, A. E., Westveld, A. H. and Goldman, T. (2005). Calibrated probabilistic forecasting using ensemble model output statistics and minimum CRPS estimation. *Monthly Weather Review*, 133, 1098-1118.
- [3] Gneiting, T., Stanberry, L. I., Grimit, E. P., Held, L. and Johnson, N. A. (2008). Assessing probabilistic forecasts of multivariate quantities, with applications to ensemble predictions of surface winds. *Test*, 17, 211-235.
- [4] Möller, A., Lenkoski, A. and Thorarinsdottir, T. (2012). Multivariate probabilistic forecasting using Bayesian model averaging and copulas. To appear in *Quarterly Journal of the Royal Meteorological Society*.
- [5] Pinson, P. (2012). Adaptive calibration of (u, v) -wind ensemble forecasts. *Quarterly Journal of the Royal Meteorological Society*, 138, 1273-1284.
- [6] Raftery, A. E., Gneiting, T., Balabdaoui, F. and Polakowski, M. (2005). Using Bayesian model averaging to calibrate forecast ensembles. *Monthly Weather Review*, 133, 1155-1174.
- [7] Schuhen, N., Thorarinsdottir, T. and Gneiting, T. (2012). Ensemble model output statistics for wind vectors. *Monthly Weather Review*, 140, 3204-3219.